Exposing New Vulnerabilities of Error Handling Mechanism in CAN

Khaled Serag⁺, Rohit Bhatia⁺, Vireshwar Kumar^{*}, Z. Berkay Celik⁺, Dongyan Xu⁺

+ Purdue University*Indian Institute of Technology Delhi



- CAN: Communication protocol for automobiles and industrial automation
 - Wiring
 - Decentralization
 - Noise Resistance
 - Effective error handling and fault confinement mechanism
- We investigate CAN's error handling and fault confinement mechanism







- CAN Operation
 - Format





- CAN Operation
 - Format
- CAN error handling and fault confinement mechanism
 - Error Counters: TEC, REC

PurSecLab

• Error States



Standard Data Frame Format



- Attacker can remotely compromise certain ECUs (i.e., telematics)
 - Weak security of ECUs has been demonstrated



- Attacker can remotely compromise certain ECUs (i.e., telematics)
 - Weak security of ECUs has been demonstrated
- New: Attacks against error handling
 - Simultaneous transmission and collisions
 - Attacker can dictate a victim's error state
 - Security impact of error handling is understudied





- Attacker can remotely compromise certain ECUs (i.e., telematics)
 - Weak security of ECUs has been demonstrated
- New: Attacks against error handling
 - Simultaneous transmission and collisions
 - Attacker can dictate a victim's error state
 - Security impact of error handling is understudied







- Attacker can remotely compromise certain ECUs (i.e., telematics)
 - Weak security of ECUs has been demonstrated
- New: Attacks against error handling
 - Simultaneous transmission and collisions
 - Attacker can dictate a victim's error state
 - Security impact of error handling is understudied







- CAN Operation eXplorer (CANOX)
 - Explores the impact of operating outside of the error active state
 - Reveals possible vulnerabilities





CAN Operation eXplorer (CANOX)

- Explores the impact of operating outside of the error active state
- Reveals possible vulnerabilities
- Node under Test (NUT)
 - logs its metrics throughout the experiment





- Scenarios
 - Single Collision Scenario
 - Successive Transmission Scenario
 - Single Transmission Scenario





- Scenarios
 - Single Collision Scenario
 - Successive Transmission Scenario
 - Single Transmission Scenario
- Behavioral Metrics
 - Standby Delay (SD)
 - TEC Change (TECC)







- Scenarios
 - Single Collision Scenario
 - Successive Transmission Scenario
 - Single Transmission Scenario
- Behavioral Metrics
 - Standby Delay (SD)
 - TEC Change (TECC)
- Vary error state and bus traffic





- Scenarios
 - Single Collision Scenario
 - Successive Transmission Scenario
 - Single Transmission Scenario
- Behavioral Metrics
 - Standby Delay (SD)
 - TEC Change (TECC)
- Vary error state and bus traffic
- Log analyzer detects violations





• Failure to send a passive error frame generates a new error

Passive Error Frame

Error Flag	Error Delimiter
6 b (recessive)	8 b (recessive)



• Failure to send a passive error frame generates a new error



• Failure to send a passive error frame generates a new error



• Failure to send a passive error frame generates a new error



Vulnerability 2: Deterministic Recovery Behavior

• At recovery, an ECU will send the same message that failed to transmit



Vulnerability 2: Deterministic Recovery Behavior

• At recovery, an ECU will send the same message that failed to transmit



\PurSec Lab

Vulnerability 2: Deterministic Recovery Behavior

• At recovery, an ECU will send the same message that failed to transmit



PurSecLab

Vulnerability 3: Error State Outspokenness

- The error state of a message sender is detectable by any node on the bus
- This could be exploited to map the network



Vulnerability 3: Error State Outspokenness

- The error state of a message sender is detectable by any node on the bus
- This could be exploited to map the network





Vulnerability 3: Error State Outspokenness

- The error state of a message sender is detectable by any node on the bus
- This could be exploited to map the network





- Threat Model:
 - Remotely compromised ECU able to execute arbitrary code
 - No physical access or previous knowledge of the vehicle





- Threat Model:
 - Remotely compromised ECU able to execute arbitrary code
 - No physical access or previous knowledge of the vehicle





- Threat Model:
 - Remotely compromised ECU able to execute arbitrary code
 - No physical access or previous knowledge of the vehicle





- Threat Model:
 - Remotely compromised ECU able to execute arbitrary code
 - No physical access or previous knowledge of the vehicle



- Threat Model:
 - Remotely compromised ECU able to execute arbitrary code
 - No physical access or previous knowledge of the vehicle



Results

Testbed Results	ECU #	Suppression Rate
	ECU-1	99.9%
	ECU-2	99.9%
	ECU-3	99.9%
	ECU-4	99.9%



Results

Testbed Results	ECU #	Suppression Rate	
	ECU-1	99.9%	Due Off Times
	ECU-2	99.9%	$Srate = \frac{Bus Off Time}{Total Time}$
	ECU-3	99.9%	I otat I tme
	ECU-4	99.9%	



Results

Testbed Results	ECU #	Suppression Rate	
	ECU-1	99.9%	Due Off Time
	ECU-2	99.9%	$Srate = \frac{Bus OJJ Time}{Total Time}$
	ECU-3	99.9%	Totat Time
	ECU-4	99.9%	

Vehicle Results	ECU #	Function	Suppression Rate
	ECU-1	EBCM (Brake)	97.5%
	ECU-2	BCM (Body)	91.4%
	ECU-3	TCM (Transmission)	85%
	ECU-4	ECM (Engine)	83%



Demo

🜠 ub Clone [Running] - Oracle VM VirtualBox		- a x
File Machine View Input Devices Help		
Ubuntu Desktop		🎝 🖬 🖦 40) 4:54 PM (밧
QC C	ID 1: 07A	Attacker
Image: Second	ID 2: 07F	Victim
		🔽 🎯 💯 📰 🚛 🔞 🚯 Right Ctrl
Type here to search	# 🕹 🧰 🗐 💽 🐠 🌖	🔫 📕 💥 💇 🔤 🌠 😏 🛛 🔺 🖷 (1)) ENG 454 PM 🐻
PURDUE UNIVERSITY		

Responsible Disclosure

- Reported vulnerabilities to:
 - Bosch Product Security Incident Response Team (PSIRT).
 - Cybersecurity and Infrastructure Security Agency (CISA)
 - Case opened
 - Society of Automotive Engineers (SAE)
 - Committee review for next standard revision
- Proposed mitigations to each of the discovered vulnerabilities



Conclusion

- CAN's error handling mechanism a security weakness
- We introduced CANOX
 - A protocol testing tool to identify possible vulnerabilities
- Three new error-handling vulnerabilities revealed by CANOX
 - Each could be exploited separately
 - STS: an end-to-end attack via exploiting all three vulnerabilities
- Attack Implementation on a testbed and a real vehicle
 - Mapping Accuracy: 100%
 - Single Frame Bus Off Effectiveness: 100%
 - Persistent Bus Off Suppression Rate: 83-100%



Thank You! Questions?

Khaled Serag: kserag@purdue.edu

This work was supported in part by the Office of Naval Research (ONR) under Grant N00014-18-1-2674.

